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# INFLUENCE OF COUPLE STRESSES ON THE PROPAGATION OF ELASTIC WAVES IN A MICROPOLAR CUBICALLY ANISOTROPIC MEDIUM

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Expressions for the phase and radial velocities of propagation of three-dimensional fronts of quasilongitudinal and quasitransverse elastic waves in a micropolar cubically anisotropic medium have been obtained. An analysis of the influence of the micropolar elastic constant on the dependence of the wave velocities on the angle of inclination of the normal to the wave surface has been made.

The micropolar (nonsymmetric) theory of elasticity of a continuum was developed with the aim of eliminating the disagreement between theory and experiment in problems of high-frequency oscillations and describing phenomena occurring in anisotropic media in traversal of elastic waves, etc., with a sufficient degree of accuracy. The theoretical foundations of the nonsymmetric theory of elasticity of an isotropic medium have been reflected in fundamental monographs [1, 2]. The results of experimental investigations on detection of couple-stress effects have been presented in [3, 4]. The micropolar theory of elasticity of an anisotropic medium and an analysis of wave motions in such media have been the focus of [5–7]. Below, we discuss the influence of one micropolar elastic constant on the velocities of propagation of quasilongitudinal and quasitransverse waves in cubically anisotropic materials characterized by the presence of no lower than threefold axes of symmetry [8]. Media with cubic symmetry include such widespread metals and minerals as brass, lead, silver, nickel, table salt, ice, and others.

The resolving system of dynamic equilibrium equations will be represented in the following form [9]:

$$A_{3}\Delta u_{j} + A\partial_{j}^{2}u_{j} + (A_{2} + A_{4})\partial_{j}\sum_{k=1}^{3}\partial_{k}u_{k} + (A_{3} - A_{4})\sum_{k,m=1}^{3}\varepsilon_{jkm}\phi_{m,k} + \rho f_{j} = \rho\ddot{u}_{j},$$

$$B_{3}\Delta\phi_{j} + B\partial_{j}^{2}\phi_{j} + (B_{2} + B_{4})\partial_{j}\sum_{k=1}^{3}\partial_{k}\phi_{k} + (A_{3} - A_{4})\sum_{k,m=1}^{3}\varepsilon_{jkm}\partial_{k}u_{m} - 2(A_{3} - A_{4})\phi_{j} + \rho l_{j} = J\rho\ddot{\phi}_{j}.$$
(1)

The characteristic equation [10] for system (1) breaks down into two uncoupled equations:

$$(A_{3}\tau_{1} - \rho p_{0}^{2})^{3} + \tau_{1} (A_{1} - A_{3}) (A_{3}\tau_{1} - \rho p_{0}^{2})^{2} + A (A + 2 (A_{2} + A_{4})) \times \times (A_{3}\tau_{1} - \rho p_{0}^{2}) \tau_{2} + A^{2} (A + 3 (A_{2} + A_{4})) \tau_{3} = 0,$$

$$(B_{3}\tau_{1} - J\rho p_{0}^{2})^{3} + \tau_{1} (B_{1} - B_{3}) (B_{3}\tau_{1} - J\rho p_{0}^{2})^{2} + B (B + 2 (B_{2} + B_{4})) \times$$

$$(2)$$

$$\times (B_3 \tau_1 - J \rho p_0^2) \tau_2 + B^2 (B + 3 (B_2 + B_4)) \tau_3 = 0.$$
<sup>(3)</sup>

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Fig. 1. Dependences of  $v_j/v_{0j}$  on the angle  $\alpha$  of inclination of the normal to the characteristic surface: 1 and 3)  $v_1(\alpha)/v_{01}(\alpha)$  and  $v_3(\alpha)/v_{03}(\alpha)$  in the  $x_1 = 0$  (solid curves) and  $x'_1 = 0$  (dashed curves) planes; 2)  $v_2(\alpha)/v_{02}(\alpha)$  in the  $x'_1 = 0$  plane.

Next we restrict ourselves to an analysis of Eq. (2), which can be written as

$$(\tau_1 - p_0^2/c^2)^3 + \tau_1 (a - 1) (\tau_1 - p_0^2/c^2)^2 + (a - b - \varepsilon - 1) (1 + b + \varepsilon - 1) \times (\tau_1 - p_0^2/c^2) \tau_2 + (a - b - \varepsilon - 1)^2 (a + 2b + 2\varepsilon - 1) \tau_3 = 0.$$
(4)

Taking into account that  $V = -p_0/\sqrt{\tau_1}$  and  $n_j = p_j\sqrt{\tau_1}$ , from (4) we will have

$$(1 - v^{2})^{3} + (a - 1) (1 - v^{2})^{2} + (a - b - \varepsilon - 1) (a + b + \varepsilon - 1) \times (1 - v^{2}) \hat{\tau}_{2} + (a - b - \varepsilon - 1)^{2} (a + 2b + 2\varepsilon - 1) \hat{\tau}_{3} = 0$$

or

$$q_0 v^6 + \dot{q}_1 v^4 + \dot{q}_2 v^2 + \dot{q}_3 = 0.$$
<sup>(5)</sup>

In Eq. (5), we have introduced the following notation for the coefficients:  $q_0 = -1$ ,  $q_1 = (2+a)\tau_1$ ,  $\hat{q}_1 = 2+a$ ,  $\hat{q}_2 = -(1+2a) - (a-b-\epsilon-1)(a+b+\epsilon-1)\hat{\tau}_2$ , and  $\hat{q}_3 = a + (a-b-\epsilon-1)(a+b+\epsilon-1)\hat{\tau}_2 + (a-b-\epsilon-1)^2(a-1+2b+2\epsilon)\hat{\tau}_3$ .

Expressions for the velocities of propagation of elastic waves in the direction of the normal to the wave surface will be represented in the form

$$v_{j} = \sqrt{\frac{2+a}{3} + 2\sqrt{-\frac{\hat{p}}{3}}\cos\left(\frac{\hat{\Lambda}_{j} + 2\pi (4-j)}{3}\right)}, \quad \hat{\Lambda}_{j} = \arccos\left(-\frac{\hat{q}}{2}\sqrt{-\left(\frac{3}{\hat{p}}\right)^{3}}\right), \quad (6)$$
$$-\frac{\hat{q}_{1}^{2}}{3q_{0}^{2}} + \frac{\hat{q}_{2}}{q_{0}}; \quad \hat{q} = \frac{2\hat{q}_{1}^{3}}{27q_{0}^{3}} - \frac{\hat{q}_{1}\hat{q}_{2}}{3q_{0}^{2}} + \frac{\hat{q}_{3}}{q_{0}}.$$

where  $\hat{p} = -\frac{\hat{q}_1^2}{3q_0^2} + \frac{\hat{q}_2}{q_0};$ 

A comparative analysis of the inverse-velocity surfaces  $1/v_j$ , which was performed for different cubically anisotropic materials and  $\varepsilon$  values from the range 1.01–1.025, has shown that  $v_1 > v_2 \ge v_3$ . Based on the results of [2], it can be inferred that it is a quasilongitudinal wave that propagates with a velocity  $v_1$ , whereas quasitransverse waves propagate with velocities  $v_2$  and  $v_3$ .

Let us consider the dependences of  $v_j$  on the angle  $\alpha$  of inclination of the normal to the characteristic surface for the  $\varepsilon$  ratios equal to 1.25 in one coordinate plane and in the plane  $x'_1 = 0$  making an angle  $\pi/4$  with the coordinate planes  $x_10x_3$  and  $x_20x_3$ . Figure 1 gives the dependences of the ratios  $v_j(\alpha)/v_{0j}(\alpha)$  in the  $x_1 = 0$  and  $x'_1 = 0$  plane of a



Fig. 2. Dependences of  $g_i/g_{0i}$  on the angle of inclination of the normal to the characteristic surface: 1 and 3)  $g_1(\alpha)/g_{01}(\alpha)$  and  $g_3(\alpha)/g_{03}(\alpha)$  in the  $x_1 = 0$ (solid curves) and  $x'_1 = 0$  (dashed curves) planes; 2)  $g_2(\alpha)/g_{02}(\alpha)$  in the  $x'_1 = 1$ 0 plane.

cubically anisotropic material ( $v_{0i}(\alpha)$  is the dependence of the velocity of propagation of an elastic wave for  $\varepsilon = 1$ ). The elastic properties of the medium are characterized by the constants a = 3.23611 and b = 2.72222 [11].

From Fig. 1, it is clear that the maximum change in the velocities  $v_1$  and  $v_3$  as compared to the velocities  $v_{01}$  and  $v_{03}$  determined within the framework of the classical elasticity theory is observed in the plane  $x_1 = 0$  at  $\alpha =$  $\pi/4$ ; this difference is more pronounced for the quasitransverse wave ( $\approx 2\%$ ). As  $\varepsilon$  increases further, the velocity of the quasilongitudinal wave increases, whereas the velocity of the quasitransverse wave decreases as compared to  $v_1$  and  $v_3$ . In the case where  $\varepsilon < 1$  we have  $v_1(\alpha)/v_{01}(\alpha) \le 1$  and  $v_3(\alpha)/v_{03}(\alpha) \ge 1$  for any angles of inclination of the normal to the characteristic surface. The velocity of propagation of the quasitransverse wave  $v_2$  in the coordinate plane is unaffected by the micropolar elastic constant  $\varepsilon = A_4/A_3$ . In the  $x_1 = 0$  plane, couple stresses lead to an increase in the velocities of three elastic waves, including the velocity of the quasitransverse wave  $v_2$ . Its largest quantitative change in this plane amounts to  $\approx 0.8\%$  at  $\alpha = 0.6$ . The same value of the angle of inclination of the normal in the  $x_1 = 0$ plane corresponds to the maximum change in the velocity of the quasilongitudinal wave (excess of  $\approx 0.2\%$  as compared to  $v_{01}$ ). It is noteworthy that the values of the ratios  $v_j/v_{0j}$  in the  $x_1' = 0$  plane at  $\alpha = 0$  and in the  $x_1 = 0$  plane at  $\alpha = \pi/4$  exactly coincide.

The modulus of the radial velocity of propagation of an elastic wave (modulus of the velocity of propagation of wave energy) is determined by the following expression [12]:

$$G = \sqrt{\sum_{i=1}^{3} \left(\frac{\partial p_0}{\partial p_i}\right)^2} \quad . \tag{7}$$

We note that the radial velocity is numerically equal to the path traversed by wave energy in this direction per unit time [8].

We express  $p_0$  from Eq. (4):

$$\frac{p_0^{(j)}}{c} = \sqrt{\frac{(2+a)\tau_1}{3} + 2\sqrt{-\frac{p}{3}}\cos\left(\frac{\Lambda_j + 2\pi (4-j)}{3}\right)},$$
(8)

where  $\Lambda_j = \arccos\left(-\frac{q}{2}\sqrt{-\left(\frac{3}{p}\right)^3}\right)$   $p = -\frac{q_1^2}{3q_0^2} + \frac{q_2}{q_0}$ ,  $q = \frac{2q_1^3}{27q_0^3} - \frac{q_1q_2}{3q_0^2} + \frac{q_3}{q_0}$ ,  $q_1 = (2+a)\tau_1$ ;  $q_2 = -(1+2a)\tau_1^2 - \frac{q_1^2}{3q_0^2} + \frac{q_2}{3q_0^2} + \frac{q_3}{3q_0^2} + \frac{q_3}$ 

 $(a-b-\epsilon-1)(a+b+\epsilon-1)\tau_2; \ q_3 = a\tau_1^3 - (a-b-\epsilon-1)(a+b+\epsilon-1)\tau_1^2\tau_2 + (a-b-\epsilon-1)^2(a-1+2b+2\epsilon)\tau_3, \ \text{the su-supervise}$ perscript j determines the type of elastic wave.



Fig. 3. Dependences of the velocity ratios  $g_1/v_1$  and  $g_3/v_3$  on the angle  $\alpha$  of inclination of the normal to the characteristic surface in the  $x_1 = 0$  (solid curves) and  $x'_1 = 0$  (dashed curves) planes of a cubically anisotropic body.

We find the partial derivatives of  $p_0$  from (8) with respect to the parameters  $p_i$ :

$$\frac{1}{c} \frac{\partial p_0^{(j)}}{\partial p_i} = \frac{1}{v_j} \left( \frac{1}{2\sqrt{-3\hat{p}}} \left( \frac{2\hat{q}_1 q_{1i}}{3q_0^2} - \frac{q_{2i}}{q_0} \right) \cos\left( \frac{\hat{\Lambda} + 2\pi (4-j)}{3} \right) - \frac{1}{3} \sqrt{-\frac{\hat{p}}{3}} \times \sin\left( \frac{\hat{\Lambda} + 2\pi (4-j)}{3} \right) \sqrt{\frac{\hat{p}^3}{4\hat{p}^3 + 27\hat{q}^2}} \left( \left( \frac{2\hat{q}_1^2 q_{1i}}{9q_0^3} - \frac{\hat{q}_2 q_{1i} + \hat{q}_1 q_{2i}}{3q_0^2} + \frac{q_{3i}}{q_0} \right) \times \sqrt{\left(-\frac{3}{\hat{p}}\right)^3} - \frac{9\hat{q}_1 \sqrt{3}}{2} \sqrt{\left(-\frac{1}{\hat{p}}\right)^5} \left( \frac{2\hat{q}_1 q_{1i}}{3q_0^2} - \frac{q_{2i}}{q_0} \right) \right) \right), \quad i, j = \overline{1, 3}.$$
(9)

The coefficients  $q_{ki}$ , k = 1, 3, with account for  $p_j = n_j \sqrt{\tau_1}$  will be represented in the form

$$q_{1i} = (2+a) \tau_{1i}, \quad q_{2i} = (a-b-\varepsilon-1) (a+b+\varepsilon-1) \tau_{2i} - 2 (1+2a) \tau_{1i},$$
$$q_{3i} = 3a\tau_{1i} + (a-b-\varepsilon-1) (a+b+\varepsilon-1) (\tau_{1i}\hat{\tau}_2 + \hat{\tau}_1\tau_{2i}) + (a-b-\varepsilon-1)^2 (a-1+2b+2\varepsilon) \tau_{3i}$$

Substituting (9) into (7), we will have the expressions for the dimensionless radial velocities of propagation of elastic waves  $g_j = G_j/c$ . Figure 2 gives the dependences of the ratios  $g_j/g_{0j}$  on the angle  $\alpha$  in the  $x_1 = 0$  and  $x'_1 = 0$  planes of a cubically anisotropic material for  $\varepsilon = 1.025$ . The elastic properties of the material are characterized by the constants a = 3.23611 and b = 2.72222.

Figure 2 shows that the radial velocity of propagation of the quasilongitudinal wave with allowance for the micropolar effects in the  $x_1 = 0$  and  $x'_1 = 0$  planes exceeds the velocity of the elastic wave irrespective of the angle of inclination of the normal to the characteristic surface. In the  $x'_1 = 0$  plane, the influence of couple stresses on the velocity of this wave is more significant than that in the  $x_1 = 0$  plane. The velocity  $g_3$  of propagation of the quasitransverse wave in the two planes in question as a function of the angle of inclination of the normal to the velocity  $g_{03}$ ; the influence of the micropolar elastic constant in the  $x'_1 = 0$  plane is more substantial than that in the coordinate plane. In the  $x'_1 = 0$  plane, the micropolar constant affects the velocity  $g_2$  of propagation of another quasitransverse wave, too (in the  $x_1 = 0$ , the ratio  $g_2/g_{02}$  takes on a value of unity

irrespective the angle  $\alpha$  and the constant  $\varepsilon$ ). The largest deviation of the radial velocity  $g_j$  of propagation of the elastic wave for  $\varepsilon = 1.025$  from the corresponding velocity  $g_{0j}$  for  $\varepsilon = 1$  is observed in the  $x'_1 = 0$  plane at  $\alpha = 0$  for the quasitransverse wave propagating with a velocity  $g_3$  and amounts to 2.5%.

A comparative analysis of the velocities  $g_j$  and  $v_j$  of propagation of elastic waves, which has been performed for  $\varepsilon$  in the range of 0.975–1.025, shows that their ratio satisfies the inequality  $g_j/v_j \ge 1$  irrespective of the angle of inclination of the normal to the characteristic surface.

In closing, we note that formulas (9) can directly be used for determination of the coordinates of the medium's points approached by the wave disturbance by the time t, construction of three-dimensional fronts of elastic waves, and evaluation of the influence of micropolar effects on the angles and positions of lacunas occurring in propagation of quasitransverse waves.

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#### NOTATION

 $A_j$ , elastic constants;  $A_4$ , micropolar elastic constant;  $A = A_1 - A_2 - A_3 - A_4$ ;  $a = A_1/A_3$ ;  $B_j$  and  $B_4$ , micropolar elastic constants;  $B = B_1 - B_2 - B_3 - B_4$ ;  $b = A_2/A_3$ ;  $c = \sqrt{A_3/\rho}$ ;  $f_j$ , body forces; G, radial velocity;  $g_j = G_j/c$ ;  $g_{0j}$ , radial velocity of propagation of an elastic wave for  $\varepsilon = 1$ ; J, microinertia constant;  $l_j$ , body moments;  $n_j = p_j/\sqrt{\tau_1}$ , direction cosines of the normal to the wave surface;  $p_0$  and  $p_j$ , parameters;  $u_1$ ,  $u_2$ , and  $u_3$ , components of the displacement vector;  $V = -p_0/\sqrt{\tau_1}$ , phase velocity; v = V/c;  $v_{0j}$ , velocity of propagation of an elastic wave for  $\varepsilon = 1$ ;  $\alpha$ , angle of inclination of the normal to the wave surface;  $\Delta$ , Laplace operator;  $\varepsilon = A_4/A_3$ ;  $\varepsilon_{ijm}$ , alternating tensor;  $\varphi_1$ ,  $\varphi_2$ , and  $\varphi_3$ , components of the microrotation vector;  $\rho$ , density of the medium;  $\tau_1 = p_1^2 + p_2^2 + p_3^2$ ;  $\tau_2 = p_1^2 p_2^2 + p_2^2 p_3^2 + p_1^2 p_3^2$ ;  $\tau_3 = p_1^2 p_2^2 p_3^2$ ;  $\hat{\tau}_3 = n_1^2 n_2^2 n_3^2$ ;  $\hat{\tau}_2 = n_1^2 n_2^2 + n_2^2 n_3^2 + n_1^2 n_3^2$ ;  $\underline{\tau}_{1i} = 2n_i$ ;  $\tau_{2i} = 2n_i(1 - n_i^2)$ ;  $\tau_{3i} = 2n_i(\hat{\tau}_2 - n_i^2(1 - n_i^2))$ ;  $\partial_i = \partial/\partial x_i$ ; point, time differentiation. Subscripts: j, i, and m = 1, 3.

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